# Project Kifer (05 Dec 2003)

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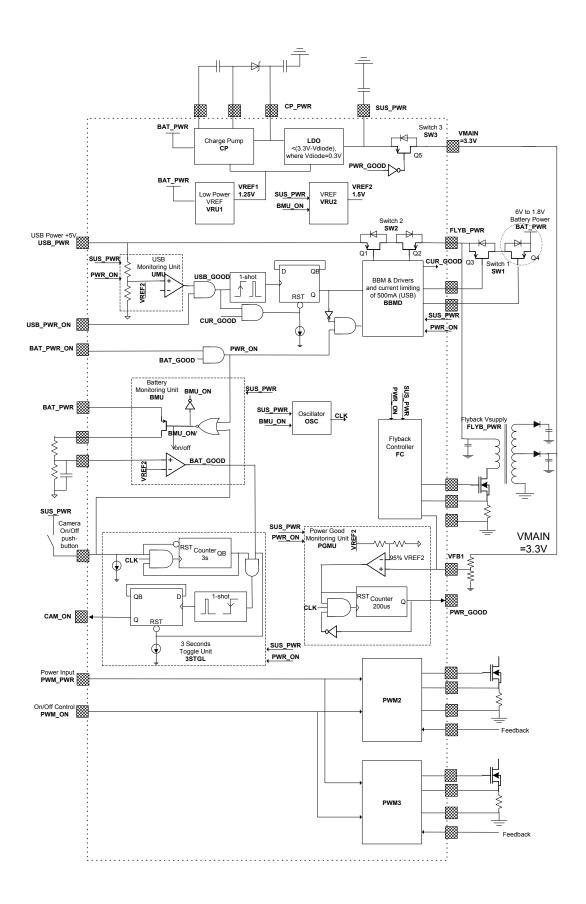
## **Block Diagram**

The block diagram of Project Kifer is as shown:

The functions of various signals are described.

Signal Name	Direction	Description
Power and Comm	unication with Ho	st
USB_PWR	From Host	+5v USB power from Host.
BAT_PWR	From Battery	Battery voltage from 1.8V to 6V.
SUS_PWR	To DSP	To power DSP and the system (Kifer) during suspend-mode.
USB_PWR_ON	From DSP	Use USB power.
BAT_PWR_ON	From DSP	Use Battery power.
PWR_GOOD	To DSP	+3.3V is good.
CAM_ON	To DSP or	The camera on/off button is pressed for at least 3 seconds. It can
	To Kifer	be connected to BAT_PWR_ON for camera to self-start.
Internal		
BMU_ON	Internal	In suspend-mode, when user press the camera on/off button, BMU_ON is asserted to enable BMU, OSC and REF. This
		ensures 3STGL is functioning to verify the user action and BMU to measure battery voltage.
BAT_GOOD	Internal	If asserted, battery voltage is good.
USB_GOOD	Internal	If asserted, USB voltage is good.
PWR_GOOD	Internal	If asserted, +3.3V is good.
PWR_ON	Internal	If BAT_GOOD=1 and BAT_PWR_ON=1, it is asserted. It is used to shut down non-essential block during the suspend- mode and turn on the entire chip during the Battery or USB powered mode.

\* When Kifer or DSP is in suspend-mode and being powered by LDO working at possible low output voltage of 1.8V, the logic high (asserted) of the signals can vary from 1.8V to 3V. Logic low is 0V.



The functions of various blocks are explained.

#### System

The desired switching frequency is 1MHz, but 600KHz is acceptable. Zoran prefers to have a fixed-frequency switching system. However, a variable-frequency scheme will be adopted first.

#### Transformer

The transformer will have several taps to deliver several voltages. Only one voltage (VMAIN) is used as feedback signal by the flyback controller.

#### Switch 1, 2, 3 and BBM & Drivers (BBMD)

The total power supplied by external sources, namely battery and USB power, is normally around 1.1W for a small camera and between 2.1W to 2.6W for a high-end camera.

1.1W is used for the design of Kifer. SW1 is off-chip taken into consideration that battery voltage can go as low as 1.8V and resulted in higher current, assuming that the power is constant. SW2 is on-chip since USB voltage is roughly equal to 5V.

SW1 will be based on FDW2508P during the simulation.

Q4 can be taken out if battery voltage is always less than USB voltage.

It is likely that battery voltage of camera is either from 1.8 to 3V or 3.6 to 6V depending on the intended battery used.

Hence for SW1, expected average current flow is 220mA (1.1/5). Likewise, 1.44A (1.1/1.8) for switch 2.

A sensing mechanism must be in place to monitor the current through SW1. The current should be limited to 500mA according the USB specification. Current sensing circuit might not be accurate, but the absolute maximum of 500mA should not be exceeded. If above the limited, SW1 must be turned off.

One of the outputs, driving the SW1 can be used to let DSP knows that Kifer switched on battery despite the permission to use USB power. To unlatch this, DSP should toggle USB\_PWR\_ON.

Q5 body diode will allow VMAIN to start to supply current to SUS\_PWR when VMAIN is greater than SUS\_PWR. When PWR\_GOOD=1, Q5 is on and VMAIN taken over SUS\_PWR and LDO is off. The turning on of Q5 should be soft and turning off can be sharp (advice from Vlad).

BBMD controls the switching of voltage from battery to USB or vice-versa.

When USB\_PWR\_ON is asserted, SW2 must be opened and SW1 closed. Both switches should not be on at the same time since voltage level of battery and USB Power are different. At the instance when both switches are off, the system should remain powered. The inrush current drawn from USB during switch on of SW2 should be avoided. << BBM and timing control needed to ensure this>>.

The sequences of switch-over of supply are as shown.

Switch-over from USB_PWR to BAT_PWR 6V to 1.8V			Switch-over from BAT_PWR to USB_PWR		
USB Power +5V Switt USB_PWR USB_PWR USB_PWR USB_PWR USB_PWR USB_PWR USB_PWR	ch 2 Switch 1 Battery Po	wer USB Dower (5)/	Switch 2 Sw2 Sw2 Sw2 Sw2 Sw2 Sw2 Sw2 Sw2 Sw1 Sw1 Sw1 Switch 2	Switch 1 SW1	6V to 1.8V Battery Power BAT_PWR
USB-powered-mode		Battery-powered-mode	->		
Q2 off and Q4 on Higher voltage supply		Q3 off and Q1 on Higher voltage supply SUS_PWR			
Q1 off HILE SUS_PWR		Q4 off USB_PWR supply SUS_PWR			-₽-
Q3 on Battery-powered-mode — 🖌 — 🖂		Q2 on USB-powered-mode			- <del>N</del>

#### **Battery Monitoring Unit (BMU)**

The battery voltage is monitored for protection of battery. If the voltage level is less than a set voltage, BAT\_GOOD=0. The switch is used to prevent loading by the two resistors. The unit is only off in the suspend-mode.

Assuming battery (AA alkaline) internal ESR= $0.2\Omega$ . With 2 cells battery, the total internal ESR= $0.4\Omega$ . When battery internal voltage is 2.04V and sourcing 0.6A, the battery external voltage is 1.8V. Hence the minimum low threshold voltage level of BMU is 1.8V. Below 1.8V, the circuit design is difficult.

Let us assume high threshold voltage level of BMU is 2.0V. When the camera just turn on, when flyback converter is not yet operating, the battery external voltage could be closed to 2.04V and hence BAT\_GOOD=1. After PWR\_GOOD=1, the battery external voltage could drop to <1.8V and hence the camera will shut-down. To avoid such 'chattering' situation, the high threshold voltage level should be set higher.

#### **USB Monitoring Unit (UMU)**

The USB voltage is monitored for the presence of USB. If the voltage level is less than a set voltage, USB\_GOOD=0. The unit is only on in the USB-powered-mode.

#### **Power Good Monitoring Unit (PGMU)**

VMAIN is monitored. When it is above a threshold, counter is activated. After 200us, PWR\_GOOD is asserted. If VMAIN drop below the threshold, PWR\_GOOD is immediately de-asserted.

#### Linear Regulator (LDO)

When BAT\_PWR>3V, LDO output voltage should be fixed at 3V. When BAT\_PWR<3V, LDO output voltage should be closed to BAT\_PWR with certain dropout voltage <<of 50 to 80mV>>. The LDO must work as long as battery supply voltage is present in the camera. During suspend-mode, 20uA is expected from LDO to supply to DSP. LDO has to be able to supply enough current to start-up each block when entering into battery-powered-mode, since SUS\_PWR is supplying Kifer during suspend-mode. The quiescent current of the LDO must be <**1uA** <<<Pre>CP and VRU1 will draw more than this>> in any condition.

#### 3 Seconds Toggle Unit (3STGL)

During the suspend-mode, when the camera on/off button is pressed, VRU, OSC and BMU is turned on. If counter reaches 3 seconds of counting and the BAT\_GOOD=1, CAM\_ON is asserted. DSP will have to assert BAT\_PWR\_ON before the user releases the button, in order to have PWR\_ON=1.

Alternately, CAM\_ON can be connected to BAT\_PWR\_ON for camera to self-start without DSP instruction.

During battery-powered-mode or USB-powered-mode, when the button is pressed for 3 seconds, CAM\_ON will be de-asserted for DSP to initiate a camera shut-down action. It is assumed that BAT\_GOOD=0 will result in PWR\_ON=0 and hence PWR\_GOOD=0. DSP will know that some conditions have resulted in PWR\_GOOD=0 and battery voltage too low is one of them.

Any pressing of button of less than 3 seconds is interpreted as accidental action of the user and logic level of CAM\_ON will not be changed.

#### Low Power Voltage Reference Unit (VRU1)

It generates the voltage reference for CP and LDO. Its accuracy is not important but current consumption must be very low.

#### High Accuracy Voltage Reference Unit (VRU2)

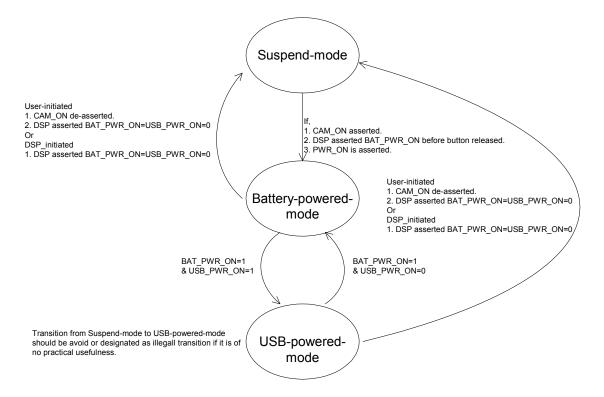
This provides an accurate voltage reference for Kifer.

#### **Oscillator (OSC)**

An external Capacitor might be needed to provide the timing unless 3 seconds and 200us do not need to be accurate. <<refer to Kea 512KHz osc>>

### **Transition Diagram**

The transition diagram of Kifer is as shown:



There are three modes of operation for Kifer as shown in the table.

Mode	BAT_PWR_ON	USB_PWR_ON	Remarks
Suspend-mode	0	0	
Battery-powered-mode	1	0	
USB-powered-mode	1	1	
Illegal mode	0	1	Do not use

During suspend-mode, PWR\_ON=0, PWR\_GOOD=0 and all circuit are shut down except VRU1, CP and LDO. LDO is providing the SUS\_PWR for DSP and some logic gates of Kifer.

When the user presses the camera on/off button while in suspend-mode, BMU will wake up to make voltage measurement of battery. OSC and VRU will wake up in order for BMU and 3GTGL to function. Once 3 seconds is reached, CAM\_ON is asserted. DSP responds by asserting BAT\_PWR\_ON=1. If the battery voltage is correct, PWR\_ON=1. Note that BAT\_PWR\_ON must be asserted before user release the camera on/off button. Once PWR\_ON=1, BMU, OSC, VRU2 will remain on for the next sequence of actions. SW1 is turned on to connect BAT\_PWR to FLYB\_PWR. FC and PGMU is turned on. Once VMAIN is correct, PWR\_GOOD=1. Then VMAIN is connected to SUS\_PWR and LDO is off automatically. Prior to PWR\_GOOD=1, the circuits draw power from SUS\_PWR.

To transit to USB-powered-mode, USB\_PWR\_ON is asserted. If USB\_GOOD=1, then SW2 will be on and SW1 off. The in-rush current of USB\_PWR due to the switch-over period should be avoided. The USB\_PWR will be current sensed and limited or protected to 500mA.

While in Battery-powered-mode or USB-powered-mode, and the user presses the camera on/off button for 3 seconds, CAM\_ON is de-asserted. DSP then de-asserted BAT\_PWR\_ON, which resulted in PWR\_ON=0. All circuits and switches will be off. LDO is on to take over SUS\_PWR.

<<Suggest ion: UMU's opamp is on only if PWR\_ON=1 and USB\_PWR\_ON=1.>>

# Specification

### **Recommended Operating Conditions**

	MIN	NOM	MAX	UNIT
Operating Junction Temperature Range, Tj	-40		125	°C
Supply Voltage (From Battery)	1.8		6	V
Supply Voltage (From USB)	4.375		5.25	V

PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT
<b>USB Monitoring Unit, Com</b>			•	·	·
High Voltage Threshold			4.5		V
Low Voltage Threshold			4.375		V
<b>Battery Monitoring Unit, C</b>	omparator		-		
High Voltage Threshold			2.1		V
Low Voltage Threshold			1.8		V
VRU1		1.	T		L = -
Supply Voltage	From Battery	2		6	V
Reference Voltage	Don't need to be accurate, but		1.25		V
	low power				
CD					1
CP Sumple Valtage	Enome Dottom			6	V
Supply Voltage Output Voltage	From Battery	2		6 5	V
Output voltage		3		3	v
LDO					
Supply Voltage	From CP	2.5		5	V
Output Voltage	During start-up	2.5	3.3	5	V
ouput foruge	During suspend-mode	2.0	2		V
Output Current	During start-up	10	-		mA
	During suspend-mode		20		uA
	<u> </u>				
Supply Voltage of Kifer (ex	cept LDO, CP, VRU1)		•	•	
Supply Voltage	From SUS_PWR	2.5		5	V
Switch 2, Q1 and Q2					
Ron of Q1	At VGS≈5V		0.5		Ω
Ron of Switch 2	At VGS≈5V		1		Ω
USB Current Protection	· · · · · · · · · · · · · · · · · · ·		·	·	·
Current Limit		400	450	500	mA

